Nonuniform decay rates for systems of differential equations

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Structure

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 - Resolvent estimates
 - Rational decay of energy
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 - Stability and rational decay rates
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Part I:

A Coupled Wave-Heat System in 1D

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Coupled Wave–Heat Systems

- Boundary coupled PDEs are used to describe, e.g., fluid-structure and heat-struture interactions.
- Coupling often leads to rational decay of energy.



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Background and Motivation

- Our model based on coupled 2D and 3D systems studied by Avalos, Triggiani and others.
- Energy decay in related 1D models studied previously using Riesz basis methods
- Research also related to a more general field of coupled PDEs, by Mercier, Nicaise, Ammari, Zuazua, Guo and many others. (also nonuniform rates have been studied for many systems of this class)

Our aim was to use resolvent estimates to simplify analysis (Avalos and Triggiani use resolvent estimates, but for general geometries the analysis becomes involved).

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1D Wave–Heat Model

$$\begin{aligned} u_{tt}(\xi,t) &= u_{\xi\xi}(\xi,t), & \xi \in (-1,0), \ t > 0, \\ w_t(\xi,t) &= w_{\xi\xi}(\xi,t), & \xi \in (0,1), \ t > 0, \\ u_{\xi}(-1,t) &= 0, & w(1,t) = 0, & t > 0, \\ u_{\xi}(0,t) &= w_{\xi}(0,t), & u_t(0,t) = w(0,t), & t > 0, \end{aligned}$$

 $\begin{cases} w_{\text{Ave-Heat Systems of ODEs}} & \text{Introduction} \\ \text{One-Dimensional Model} \\ \text{Decay of Energy} \\ \text{Optimality of the Decay Rate} \end{cases} \\ \begin{cases} u_{tt}(\xi,t) = u_{\xi\xi}(\xi,t), & \xi \in (-1,0), \ t > 0, \\ w_t(\xi,t) = w_{\xi\xi}(\xi,t), & \xi \in (0,1), \ t > 0, \\ u_{\xi}(-1,t) = 0, & w(1,t) = 0, & t > 0, \\ u_{\xi}(0,t) = w_{\xi}(0,t), & u_t(0,t) = w(0,t), & t > 0, \end{cases}$



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 $\begin{cases} w_{\text{Ave-Heat Systems of ODEs}} \\ \text{Infinite Systems of ODEs} \\ \text{Infinite Systems of ODEs} \\ \text{Conclusions} \end{cases} \begin{array}{l} \text{Introduction} \\ \text{One-Dimensional Model} \\ \text{Decay of Energy} \\ \text{Optimality of the Decay Rate} \end{cases} \\ \begin{cases} u_{tt}(\xi,t) = u_{\xi\xi}(\xi,t), & \xi \in (-1,0), \ t > 0, \\ w_t(\xi,t) = w_{\xi\xi}(\xi,t), & \xi \in (0,1), \ t > 0, \\ u_{\xi}(-1,t) = 0, & w(1,t) = 0, & t > 0, \\ u_{\xi}(0,t) = w_{\xi}(0,t), & u_t(0,t) = w(0,t), & t > 0, \end{cases} \end{cases}$



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1D Wave-Heat Model

$$\begin{cases} u_{tt}(\xi,t) = u_{\xi\xi}(\xi,t), & \xi \in (-1,0), \ t > 0, \\ w_t(\xi,t) = w_{\xi\xi}(\xi,t), & \xi \in (0,1), \ t > 0, \\ u_{\xi}(-1,t) = 0, & w(1,t) = 0, & t > 0, \\ u_{\xi}(0,t) = w_{\xi}(0,t), & u_t(0,t) = w(0,t), & t > 0, \end{cases}$$

Total energy of the system:

$$E_{x_0}(t) = \frac{1}{2} \int_{-1}^0 |u_{\xi}(\xi, t)|^2 + |u_t(\xi, t)|^2 d\xi + \frac{1}{2} \int_0^1 |w(\xi, t)|^2 d\xi$$

We are most interested in showing that $E_{x_0}(t)$ decays at a rational rate for all classical solutions of the system.

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Abstract Formulation

The system can be written as an abstract Cauchy problem

$$\begin{cases} x'(t) = Ax(t), & t \ge 0, \\ x(0) = x_0, \end{cases}$$

on $X=H^1(-1,0)\times L^2(-1,0)\times L^2(0,1)$ with operator

$$A = \begin{pmatrix} 0 & I & 0 \\ \Delta_{\text{wave}} & 0 & 0 \\ \hline 0 & 0 & \Delta_{\text{heat}} \end{pmatrix}$$

$$D(A) = \left\{ (u, v, w) \in H^2(-1, 0) \times H^1(-1, 0) \times H^2(0, 1) \right\}$$

$$u'(-1) = w(1) = 0, \ v(0) = w(0), \ u'(0) = w'(0) \}$$

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Semigroup Generation and Properties

Theorem

The operator A generates a uniformly bounded C_0 -semigroup $(T(t))_{t\geq 0}$ on X, $\sigma(A) \cap i\mathbb{R} = \{0\}$ and A has compact resolvent.

Proof.

We have $X = \text{Ran}(A) \oplus \text{Ker}(A)$ where $\dim \text{Ker}(A) = 1$ and Ran(A) is closed. The restriction $A|_{\text{Ran}(A)}$ generates a bounded semigroup due to Lumer–Phillips.

Relation to the total energy of the system: For initial state $x_0 = x_{01} + x_{02} \in \text{Ran}(A) \oplus \text{Ker}(A)$ the energy of x(t) satisfies

$$E_{x_0}(t) \asymp ||T(t)|_{\operatorname{Ran}(A)} x_{01}||^2.$$

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Main Result: Rational Decay of Energy

Theorem

If
$$x_0 \in D(A)$$
, then $E_{x_0}(t) = o(t^{-4})$ as $t \to \infty$.

Due to relation between energy and norms of orbits, the decay is equivalent to

$$||T_0(t)A_0^{-1}|| = O\left(\frac{1}{t^2}\right)$$

where $A_0 = A|_{\operatorname{Ran}(A)}$ and $T_0(t) = T(t)|_{\operatorname{Ran}(A)}$

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Decay of Energy

Decay of energy can be deduced from the resolvent estimates.

Theorem (Borichev & Tomilov 2010)

Let $(T(t))_{t\geq 0}$ be a uniformly bounded C_0 -semigroup on a Hilbert space X. Let A be the generator of $(T(t))_{t\geq 0}$ and suppose that $\sigma(A) \cap i\mathbb{R} = \emptyset$.

For any constant $\alpha > 0$, the following conditions are equivalent:

(i)
$$||R(is, A)|| = O(|s|^{\alpha}) \text{ as } |s| \to \infty;$$

(ii) $||T(t)A^{-1}|| = O(t^{-1/\alpha}) \text{ as } t \to \infty;$
(iii) $||T(t)x|| = o(t^{-1/\alpha}) \text{ as } t \to \infty \text{ for all } x \in D(A).$

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Resolvent Estimates

Theorem

$$||R(is, A_0)|| = O(|s|^{1/2})$$
 as $|s| \to \infty$, and $||T_0(t)A_0^{-1}|| = O(t^{-2})$.

Here we again denote $A_0 = A|_{\operatorname{Ran}(A)}$ and $T_0(t) = T(t)|_{\operatorname{Ran}(A)}$.

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Comments on the Proof

For $\boldsymbol{x} = (\boldsymbol{u}, \boldsymbol{v}, \boldsymbol{w})$ and $\boldsymbol{y} = (f, g, h)$ the equation

$$(is - A)x = y$$

is equivalent to the boundary value problems

$$\begin{split} u''(\xi) &= -s^2 u(\xi) - isf(\xi) - g(\xi), & \xi \in (-1,0), \\ v(\xi) &= isu(\xi) - f(\xi), & \xi \in (-1,0), \\ w''(\xi) &= isw(\xi) - h(\xi), & \xi \in (0,1), \\ u'(-1) &= w(1) = 0, \ v(0) = w(0), \ u'(0) = w'(0). \end{split}$$

Estimate $||R(is, A_0)y|| \leq \sqrt{|s|} ||y||$ follows from solving for (u, v, w) and using some convenient tricks in the estimates.

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Main Result: Rational Decay of Energy

Theorem

If $x_0 \in D(A)$, then $E_{x_0}(t) = o(t^{-4})$ as $t \to \infty$.

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Optimality of the Decay Rates

Locations of eigenvalues imply that $E_{x_0}(t) = o(t^{-4})$ is optimal.

Lemma

$$\sigma(A) = \Big\{ \lambda \in \mathbb{C} \ \big| \ \sqrt{\lambda} \cosh(\lambda) \cosh(\sqrt{\lambda}) + \sinh(\lambda) \sinh(\sqrt{\lambda}) = 0 \Big\}.$$

Proof.

Solve the boundary value problems equivalent to $(\lambda - A)x = 0$ for x = (u, v, w).

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Optimality of the Decay Rates

A Rouché argument implies:

Theorem

There exists $(\lambda_n) \subset \sigma(A)$ such that $\operatorname{Im} \lambda_n \sim n\pi$ as $n \to \infty$ and

$$-\frac{1}{|\operatorname{Im}\lambda_n|^{1/2}} \lesssim \operatorname{Re}\lambda_n < 0, \quad n \ge 0.$$

In particular,

$$\limsup_{|s| \to \infty} |s|^{-1/2} ||R(is, A)|| > 0$$

$$E_{x_0}(t) = o(t^{-4})$$
 is optimal for $x_0 \in D(A)$.



Background Motivation from Semigroup Theory Introduction to the Models Main Results

Part II:

Infinite Systems of Differential Equations

Main Problem

Study asymptotics of infinite systems of the form

$$\dot{x}_k(t) = A_0 x_k(t) + A_1 x_{k-1}(t), \quad k \in \mathbb{Z}, \ t \ge 0,$$

where $A_0, A_1 \in \mathbb{C}^{m \times m}$ do not depend on $k \in \mathbb{Z}$.

We want to study, e.g.,

$$\sup_{k\in\mathbb{Z}} \|x_k(t) - y_k\|_{\mathbb{C}^m} \to 0, \qquad \text{as} \quad t\to\infty$$

with rates.



Martinez '11, Batty, Chill & Tomilov '13 ('16), Chill & Seifert '16

Background Motivation from Semigroup Theory Introduction to the Models Main Results

Infinite Systems of Differential Equations

Our system can be formulated as an abstract Cauchy problem

 $\dot{x}(t) = Ax(t), \qquad x(0) = x_0 \in X$

on $X=\ell^p(\mathbb{C}^m)$ for $1\leq p\leq\infty$ by choosing $x(t)=(x_k(t))_{k\in\mathbb{Z}}$ and

$$Ax = (A_0x_k + A_1x_{k-1})_{k \in \mathbb{Z}}.$$

i.e.

$$A = \begin{pmatrix} \ddots & \ddots & & & \\ & A_1 & A_0 & & \\ & & A_1 & A_0 & \\ & & & \ddots & \ddots & \end{pmatrix}$$

Here $A \in \mathcal{L}(X)$ and our system belongs to the class of "Spatially invariant systems" (Barnieh et. al. and others).

Background Motivation from Semigroup Theory Introduction to the Models Main Results

A Concrete Model: An Infinite Vehicle Platoon

$$\begin{pmatrix} \dot{y}_k \\ \dot{w}_k \\ \dot{a}_k \end{pmatrix} = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -\alpha_0 & -\alpha_1 & -\alpha_2 \end{pmatrix} \begin{pmatrix} y_k \\ w_k \\ a_k \end{pmatrix} + \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} y_{k-1} \\ w_{k-1} \\ a_{k-1} \end{pmatrix}$$

Background Motivation from Semigroup Theory Introduction to the Models Main Results

A Concrete Model: An Infinite Vehicle Platoon

$$\begin{pmatrix} \dot{y}_k \\ \dot{w}_k \\ \dot{a}_k \end{pmatrix} = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -\alpha_0 & -\alpha_1 & -\alpha_2 \end{pmatrix} \begin{pmatrix} y_k \\ w_k \\ a_k \end{pmatrix} + \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} y_{k-1} \\ w_{k-1} \\ a_{k-1} \end{pmatrix}$$



Figure: Source: Ploeg et. al., IEEE, 2011.

Background Motivation from Semigroup Theory Introduction to the Models Main Results

A Concrete Model: An Infinite Vehicle Platoon

$$\begin{pmatrix} \dot{y}_k \\ \dot{w}_k \\ \dot{a}_k \end{pmatrix} = \underbrace{\begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -\alpha_0 & -\alpha_1 & -\alpha_2 \end{pmatrix}}_{= A_0} \begin{pmatrix} y_k \\ w_k \\ a_k \end{pmatrix} + \underbrace{\begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}}_{= A_1} \begin{pmatrix} y_{k-1} \\ w_{k-1} \\ a_{k-1} \end{pmatrix}$$

 $y_k(t) =$ displacement from ideal distance between k and k-1 $w_k(t) =$ velocity of kth vehicle $a_k(t) =$ acceleration of kth vehicle

Objective: Choose $\alpha_0, \alpha_1, \alpha_2 \in \mathbb{R}$ so that $\sup_{k \in \mathbb{Z}} |y_k| \to 0$ as $t \to \infty$. Challenge: The matrices A_0 and A_1 do not commute.

Background Motivation from Semigroup Theory Introduction to the Models Main Results

A More Abstract Class

Assumption

Assume $A_1 \neq 0$, $\sigma(A_0) \subset \mathbb{C}_-$, and there exists $\phi : \mathbb{C} \to \mathbb{C}$ s.t.

$$A_1(\lambda - A_0)^{-1}A_1 = \phi(\lambda)A_1, \qquad \lambda \in \mathbb{C} \setminus \sigma(A_0).$$

 $\phi(\cdot)$ is called *characteristic function* of the infinite system.

Lemma

If A_1 is of rank one such that $A_1 = ab^* \in \mathbb{C}^{m \times m}$, then

$$\phi(\lambda) = b^* (\lambda - A_0)^{-1} a.$$

Clearly $\phi(\lambda) = \frac{n(\lambda)}{d(\lambda)}$ where $\deg n(\cdot) \leq \deg d(\cdot)$.

Main Results

In the following we will do the following:

- (i) Characterize spectrum of \boldsymbol{A}
- (ii) Present conditions for uniform boundedness of T(t)
- (iii) Study rates of convergence of $||T(t)x_0 y|| \to 0$ as $t \to \infty$.

For all these purposes use the characteristic function $\phi(\cdot)$:

$$A_1(\lambda - A_0)^{-1}A_1 = \phi(\lambda)A_1, \qquad \lambda \in \mathbb{C} \setminus \sigma(A_0).$$

Main idea: Existence of $\phi(\cdot)$ compensates for the lack of commutativity of A_0 and A_1 .

Background Motivation from Semigroup Theory Introduction to the Models Main Results

Spectrum of the System

Characteristic function $\phi(\cdot)$ determines the spectrum of A:

Theorem

Let
$$X = \ell^p(\mathbb{C}^m)$$
 with $1 \le p \le \infty$. Then for $\lambda \in \mathbb{C} \setminus \sigma(A_0)$

$$\lambda \in \sigma(A) \qquad \text{if and only if} \qquad |\phi(\lambda)| = 1.$$

Moreover, for $\lambda \in \sigma(A) \setminus \sigma(A_0)$ we have

- $\operatorname{Ker}(\lambda A) \neq \{0\}$ if and only if $p = \infty$
- $\overline{\operatorname{Ran}(\lambda A)} = X$ if and only if 1 .

The type of spectrum depends on p, but the location does not.

Spectrum of the Platoon System

$$\begin{pmatrix} \dot{y}_k \\ \dot{w}_k \\ \dot{a}_k \end{pmatrix} = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -\alpha_0 & -\alpha_1 & -\alpha_2 \end{pmatrix} \begin{pmatrix} y_k \\ w_k \\ a_k \end{pmatrix} + \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} y_{k-1} \\ w_{k-1} \\ a_{k-1} \end{pmatrix}$$

Characteristic function: $\phi(\lambda) = \frac{\alpha_0}{p(\lambda)} = \frac{\alpha_0}{\lambda^3 + \alpha_2 \lambda^2 + \alpha_1 \lambda + \alpha_0}.$

Spectrum of the platoon system is determined by α_0 , α_1 , and α_2 .



Background Motivation from Semigroup Theory Introduction to the Models Main Results

Uniform Boundedness of the Semigroup

Theorem

Let
$$1 \leq p \leq \infty$$
. If $\sigma(A) \subset \mathbb{C}_{-} \cup \{0\}$,

$$\sup_{0<\lambda\leq 1}\frac{\lambda}{1-|\phi(\lambda)|}<\infty\quad\text{and}\quad \sup_{n\in\mathbb{N}}\,\sup_{\lambda>0}\;\frac{\lambda^{n+1}}{n!}\sum_{\ell=1}^{\infty}\left|\frac{d^n}{d\lambda^n}\phi(\lambda)^\ell\right|<\infty,$$

then the semigroup generated by A is uniformly bounded.

Proof.

A fairly direct Hille–Yosida approach using a resolvent formula.

Property: Systems for $m \ge 2$ are typically not contractive. In particular, the platoon system is <u>never</u> contractive.

Background Motivation from Semigroup Theory Introduction to the Models Main Results

Uniform Boundedness for the Platoon System

Lemma

If $\phi(\cdot)$ is such that for some $\zeta > 0$, $q \in \mathbb{N}$,

$$\phi(\lambda) = \frac{\zeta^q}{(\lambda + \zeta)^q}, \qquad \lambda \neq -\zeta$$

then

$$\sup_{n\in\mathbb{N}}\sup_{\lambda>0} \frac{\lambda^{n+1}}{n!}\sum_{\ell=1}^{\infty} \left|\frac{d^n}{d\lambda^n}\phi(\lambda)^{\ell}\right| < \infty.$$



The characteristic function of the platoon system is of this form if parameters $\alpha_0, \alpha_1, \alpha_2$ are chosen so that $\sigma(A_0) = \{-\zeta\}$.

Then the platoon system is guaranteed to be uniformly bounded.

Background Motivation from Semigroup Theory Introduction to the Models Main Results

(Unquantified) Asymptotic Behaviour

Combining the results on spectrum and uniform boundedness:

Theorem

Let $X = \ell^p(\mathbb{C}^m)$ and

$$\phi(\lambda) = \frac{\zeta^q}{(\lambda + \zeta)^q}, \qquad \lambda \neq -\zeta.$$

• If 1 , then <math>T(t) is strongly stable, i.e., $T(t)x \rightarrow 0$

• If p = 1, then $T(t)x \to 0$ as $t \to \infty$ for all $x \in \overline{\operatorname{Ran}(A)} \neq X$.

• If $p = \infty$ and $x = x_0 + x_1 \in \overline{\operatorname{Ran}(A)} \oplus \operatorname{Ker}(A) \neq X$, then

$$T(t)x \to x_1$$
 as $t \to \infty$.

Background Motivation from Semigroup Theory Introduction to the Models Main Results

Rates of Convergence

Next aim: Find rates of convergence for

 $\|T(t)x\| \to 0 \qquad \text{as} \quad t \to \infty$

and

$$\|T(t)x - y\| \to 0 \qquad \text{as} \quad t \to \infty$$

under the assumption $\sigma(A) \cap i\mathbb{R} = \{0\}.$



Background Motivation from Semigroup Theory Introduction to the Models Main Results

From Resolvent Estimates Near 0 to Rates

Theorem (Martinez, Chill–Seifert)

Let T(t) generated by $A \in \mathcal{L}(X)$ be uniformly bounded and $\sigma(A) \cap i\mathbb{R} = \{0\}$. If for some $\alpha \ge 1$ we have

$$\|R(is,A)\| = O(|s|^{-\alpha}) \qquad \text{as} \qquad |s| \to 0$$

then

$$||T(t)Ax|| = O\left(\left(\frac{\log t}{t}\right)^{1/\alpha}\right), \quad t \to \infty.$$

By Batty–Chill–Tomilov '13, logarithm can be omitted if X Hilbert.

Background Motivation from Semigroup Theory Introduction to the Models Main Results

Convergence Rates via Resolvent Estimates

Theorem

Let $1 \le p \le \infty$. If $0 \in \sigma(A) \subset \mathbb{C}_{-} \cup \{0\}$, then for $0 < s \le 1$

$$||R(is, A)|| \approx \frac{1}{|1 - |\phi(is)||} = O(|s|^{-n_{\phi}})$$

for an even integer $n_{\phi} \geq 2$. Thus if T(t) is uniformly bounded and $x = x_0 + x_1 \in \text{Ran}(A) \oplus \text{Ker}(A)$, then

$$||T(t)x - x_1|| = O\left(\left(\frac{\log t}{t}\right)^{1/n_{\phi}}\right)$$

Batty, Chill & Tomilov '13: Logarithm can be omitted if p = 2. (Note that $x_1 = 0$ if $1 \le p < \infty$)

Background Motivation from Semigroup Theory Introduction to the Models Main Results

Decay Rates for the Platoon System

For the platoon system, the possible exponents n_{ϕ} are 2, 4 and 6.



Corresponding rates are $\left(\frac{\log t}{t}\right)^{-\frac{1}{2}}$, $\left(\frac{\log t}{t}\right)^{-\frac{1}{4}}$ and $\left(\frac{\log t}{t}\right)^{-\frac{1}{6}}$ (though uniform boundedness was just shown for the first case).

Background Motivation from Semigroup Theory Introduction to the Models Main Results

Characterizing Initial States Leading to Convergence

Problem

Characterize elements $x \in \operatorname{Ran}(A)$ and $x \in \overline{\operatorname{Ran}(A)}$.

Motivation: Initial states $x_0\in {\rm Ran}(A)\oplus {\rm Ker}(A)$ lead to convergence with rate

$$||T(t)x_0|| \le M \left(\frac{\log t}{t}\right)^{1/n_{\phi}} ||A^{-1}x_0||.$$

In the cases $X=\ell^1(\mathbb{C}^m)$ and $X=\ell^\infty(\mathbb{C}^m)$

 $t \mapsto T(t)x$

converges to some $y \in X$ if and only if $x \in \overline{\operatorname{Ran}(A)} \oplus \operatorname{Ker}(A)$.

Theorem

Let
$$X = \ell^{\infty}(\mathbb{C}^m)$$
, $0 \in \sigma(A) \subset \mathbb{C}_- \cup \{0\}$, $T(t)$ is bdd, $\phi'(0) \neq 0$.

 $x \in \overline{\operatorname{Ran}(A)} \oplus \operatorname{Ker}(A)$ if and only if there exists $y_0 \in \operatorname{Ran}(A_1)$

$$\sup_{k \in \mathbb{Z}} \left\| \frac{1}{n} \sum_{j=1}^{n} \phi(0)^{j-k} A_1 A_0^{-1} x_{k-j} - y_0 \right\|_{\mathbb{C}^m} \to 0, \quad n \to \infty, \quad (1)$$

Theorem

Let
$$X = \ell^{\infty}(\mathbb{C}^m)$$
, $0 \in \sigma(A) \subset \mathbb{C}_- \cup \{0\}$, $T(t)$ is bdd, $\phi'(0) \neq 0$.

 $x \in \overline{\operatorname{Ran}(A)} \oplus \operatorname{Ker}(A)$ if and only if there exists $y_0 \in \operatorname{Ran}(A_1)$

$$\sup_{k \in \mathbb{Z}} \left\| \frac{1}{n} \sum_{j=1}^{n} \phi(0)^{j-k} A_1 A_0^{-1} x_{k-j} - y_0 \right\|_{\mathbb{C}^m} \to 0, \quad n \to \infty, \quad (1)$$

Moreover, if the decay in (1) is like $O(n^{-1})$ as $n \to \infty$ then $x = x_0 + x_1 \in \text{Ran}(A) \oplus \text{Ker}(A)$ and

$$||T(t)x - x_1|| = O\left(\left(\frac{\log t}{t}\right)^{1/n_{\phi}}\right), \quad t \to \infty.$$

Background Motivation from Semigroup Theory Introduction to the Models Main Results

Decay for the Platoon System

$$\begin{pmatrix} \dot{y}_k \\ \dot{w}_k \\ \dot{a}_k \end{pmatrix} = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -\zeta^3 & -3\zeta^2 & -3\zeta \end{pmatrix} \begin{pmatrix} y_k \\ w_k \\ a_k \end{pmatrix} + \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} y_{k-1} \\ w_{k-1} \\ a_{k-1} \end{pmatrix}$$

Theorem

Let $X = \ell^{\infty}(\mathbb{C}^3)$. T(t)x converges if and only if there exists $c \in \mathbb{R}$

$$\sup_{k\in\mathbb{Z}} \left| c - \frac{1}{n} \sum_{j=1}^{n} y_{k-j}(0) \right| \to 0, \quad n \to \infty,$$

and if this holds then $T(t)x \rightarrow x_1$, where

$$x_1 = \left(\dots, \begin{pmatrix} c \\ -\zeta c/3 \\ 0 \end{pmatrix}, \begin{pmatrix} c \\ -\zeta c/3 \\ 0 \end{pmatrix}, \begin{pmatrix} c \\ -\zeta c/3 \\ 0 \end{pmatrix}, \dots \right).$$

Background Motivation from Semigroup Theory Introduction to the Models Main Results

Quantified Decay for the Platoon System

$$\begin{pmatrix} \dot{y}_k \\ \dot{w}_k \\ \dot{a}_k \end{pmatrix} = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -\zeta^3 & -3\zeta^2 & -3\zeta \end{pmatrix} \begin{pmatrix} y_k \\ w_k \\ a_k \end{pmatrix} + \begin{pmatrix} 0 & -1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} y_{k-1} \\ w_{k-1} \\ a_{k-1} \end{pmatrix}$$

Theorem

Let
$$X = \ell^{\infty}(\mathbb{C}^3)$$
. If there exists $c \in \mathbb{R}$

$$\sup_{k \in \mathbb{Z}} \left| c - \frac{1}{n} \sum_{j=1}^{n} y_{k-j}(0) \right| = O\left(\frac{1}{n}\right) \quad \text{as} \quad n \to \infty,$$

then $||T(t)x - x_1|| = O(\frac{1}{\sqrt{t}})$ where again $x_1 = ((c, -\zeta c/3, 0)^T)_{k \in \mathbb{Z}}$

Here the logarithm was removed using N. Dungey 2008.

Infinite Systems of PDEs

Ideas for systems consisting of infinite coupled PDEs.

Two types of couplings:

- Inside the domain
- Through shared boundaries

An Infinite System of Heat Equations

One-dimensional systems on (0, 1):

$$\begin{split} u^k_t(\xi,t) &= u^k_{\xi\xi}(\xi,t) + \gamma u^{k-1}(\xi,t) \\ u^k(0,t) &= u^k(1,t) = 0 \\ u^k(\xi,0) &= u^k_0(\xi) \end{split}$$



for $k \in \mathbb{Z}$.

Full system $x(t)=(u^k(\cdot,t))_{k\in\mathbb{Z}}\in\ell^2(L^2(0,1))$ $Ax=(x_k''+\gamma x_{k-1})_{k\in\mathbb{Z}}$

for
$$x = (x_k)_{k \in \mathbb{Z}} \in \ell^2(H^2 \cap H^1_0).$$



An Infinite System of Heat Equations



An Infinite System of Heat Equations



Infinite Wave–Heat System with Boundary Coupling



$$A = \begin{pmatrix} \ddots & \ddots & \ddots & & \\ & A_{-1} & A_0 & A_1 & & \\ & & A_{-1} & A_0 & A_1 & \\ & & & A_{-1} & A_0 & A_1 \\ & & & & \ddots & \ddots & \ddots \end{pmatrix}$$

Infinite Network of PDEs



A doubly infinite block operator matrix with finite bandwidth.

$$A = \begin{pmatrix} \ddots & \ddots & \ddots & & \\ & * & * & * & \\ & & * & * & * \\ & & & \ddots & \ddots & \ddots \end{pmatrix}$$

References

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Thank You!