A Control-Theoretic Approach to Stability of PDE Networks

Lassi Paunonen

Tampere University, Finland

Joint work with David Seifert and Serge Nicaise

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Main Objectives

Problem

Study dynamics of networks consisting of Partial Differential Equations (PDEs), with focus on **long-time behaviour of the energy**.

Motivation:

- Dynamics of networked systems are interesting!
- Both network structure and component dynamics contribute
- $\bullet\,$ We focus on what happens when $t\to\infty$

What are PDE networks?

Throughout the talk a "PDE network" refers to

A collection of Partial Differential Equation models whose the connectivity can be described by a graph.

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Perhaps some examples will illustrate the concept...

Motivating Examples Stability and Mixed-Type PDE Networks

Beam structures



- A truss bridge beams which are joined at their ends.
- Deflection of each beam described by a PDE **beam** equation
- Can study either dynamic behaviour or the steady state.

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Truss structures

Structure determines a graph where **the beams are the** edges and the meeting points are the nodes.



Pipe Networks

Pipe delivery networks for gas, water, and petrol can be modelled as PDE networks. PDEs are **transport equations**.



- Waterflow in channels: wave equations
- Heat or material diffusion in structures: heat or convection-diffusion equations

Couplings

Question

How do the PDEs in the network communicate?

Each PDE in the network involves:

- The actual differential equation (deflection along the beam)
- Boundary conditions (deflection, slope, strain etc at the endpoints)



 \sim The beam models interact with each other at the network nodes via their **boundary conditions**.

Examples of Boundary Couplings

Physical system: Gas pipe network

- PDE type: Transport equation
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Physical system: Truss bridge

- PDE type: Beam equation
- $\bullet\,$ Coupling: Deflections are equal and forces sum to 0 and

All expressed in terms of boundary conditions, and the number depends on the PDE type.

Dynamics and Stability

Definition (Rough, but close enough)

We say the PDE network is **stable** if all its solutions converge to a steady state as $t \to \infty$.

- Linear case \rightsquigarrow zero is the unique steady state
- Stability is often equivalent to the property that the energy of the solutions satisfies E(t) → 0 as t → ∞.

Goal

We are especially interested in the **rate** of the convergence.

Mixed-Type PDE Networks

Goal

We focus on studying **stability** of networks which involve **two different types of PDEs**.

- Beams and strings (suspension bridge).
- Wave and heat equations (fluid-structure interactions?)
- Damped and undamped strings or beams.
- (PDE networks with dynamic couplings)



Stability of Mixed-Type PDE Networks

Goal

We focus on studying **stability** of networks which involve **two different types of PDEs**.

- Stability of mixed-type networks is particularly interesting!
- Convergence of solutions often slower than exponential → "polynomial stability"
- Motivates deriving accurate (rational) convergence rates for $E(t) \rightarrow 0$



Introduction Divide-and-Cone Main Results Main Results

Part II Stability Analysis

Divide-and-Conque Main Results

Dynamics of Mixed-Type Networks



Wave equations and heat equations

Divide-and-Conque Main Results



Divide-and-Conque Main Results



Divide-and-Conque Main Results



Divide-and-Conquer Main Results



Divide-and-Conquer Main Results

Inputs and Outputs







Problem

Use the properties of the two systems to deduce stability of the coupled PDE.



Benefits:

- "Divide and conquer"
- Reduce to well-known parts
- Modularity

Introduction Divide-and-Conqu Main Results Main Results

Assumption

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Introduction Divide-and-Conqu Main Results Main Results

Assumption

- The two systems are impedance passive
 - They have no "internal sources of energy"
- System 1 is stable under (neg) output feedback
 - This often represents addition of **damping** to System 1.
- Knowledge of the transfer function $P_2(\lambda)$ of System 2
 - P₂(λ) describes how "Laplace transform of u₂ is mapped to Laplace transform of y₂", i.e., ŷ₂(λ) = P₂(λ)û₂(λ).



Main Stability Result

Theorem

Assume the following:

- The two systems are impedance passive
- System 1 becomes stable under (neg) output feedback and we know the energy decay rate $E_1(t) \rightarrow 0$
- We have an estimate for the transfer function P₂(λ) of System 2 on the imaginary axis

Then:

The network is stable and we have a very good estimate for the decay rate of $E(t) \rightarrow 0$.

A Quick Mathematical Overview

• The abstract model for the mixed-type networks is a coupled system of two **boundary control systems**,

$$\begin{aligned} \dot{z}_1(t) &= L_1 z_1(t), & t \ge 0, \\ \dot{z}_2(t) &= L_2 z_2(t), & t \ge 0, \\ G_1 z_1(t) &= K_2 z_2(t), & t \ge 0, \\ G_2 z_2(t) &= -K_1 z_1(t), & t \ge 0 \end{aligned}$$

- Has a contraction semigroup [Aalto-Malinen 2013]
- Our main results establish resolvent estimates

$$\|(is-A)^{-1}\| \le M_1(s)M_2(s), \qquad \forall s \in \mathbb{R},$$

and these lead to polynomial or semi-uniform stability.

Application to Wave-Heat Networks



Question

Decay rate for energy E(t) in a network of N wave equations and 1 heat equation?

Wave/Heat Decoupling



- In the wave network (System 1) the "output feedback" is equivalent to damping at a single exterior node.
 - \rightsquigarrow Stability results in the literature
- Transfer function $P_2(\lambda)$ of the heat equation (System 2) can be computed explicitly.

Divide-and-Conquer Main Results

Wave/Heat Decoupling





Theorem

If decay rate for classical solutions in the **decoupled** wave-network is $E_1(t) \sim t^{-\alpha}$, $\alpha > 0$, then the energy E(t) of classical solutions of the **wave-heat network** has decay

$$E(t) \sim t^{-\frac{4\alpha}{4+\alpha}}, \qquad t \to \infty.$$
 (slower)



Theorem (Using Valein–Zuazua '09)

Assume that **decoupled** wave-network is **star-shaped** with same wave speeds, and ratios of lengths of the waves are irrational numbers "of constant type". Then energy of classical solutions has decay

$$E(t) \sim t^{-\frac{4}{4N-3}}, \qquad t \to \infty.$$

A Quick Literature Survey

- PDE networks single-type
 - Valein–Zuazua, Ammari–Jellouli, Ammari–Shel, Nicaise–Valein, Kramar-Fijavž et. al., Augner, ...
- Coupled PDEs two equations or simple network structures (3–4 PDEs)
 - Zhang–Zuazua, Duyackerts, Li-Wang, Augner, Avalos–Lasiecka–Triggiani, Rao–Zhang, Avalos–Geredeli,
- Coupled abstract systems

. . .

 Ben Ait Hassi et. al., Ammari et. al., Feng–Guo, LP, Boulouz–Bounit–Hadd, Dell'Oro–LP–Seifert, ...

Conclusions

In this talk:

- Study of dynamics and stability of networks of partial differential equations of mixed type.
- Main result on energy decay rate for the full network in terms of the properties of simpler networks.
- S. Nicaise, LP, D. Seifert "Stability of Abstract Boundary-Coupled Systems", Journal of Functional Analysis, 2025.
- LP, "On polynomial stability of coupled partial differential equations in 1D" Proceedings of SOTA 2018, arXiv:1911.06715

Thank You!