

IOS superposition theorem for infinite-dimensional systems

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Journal paper:

Bachmann, Dashkovskiy, Mironchenko. Characterization of input-to-output stability for infinite-dimensional systems, IEEE TAC, 2026.

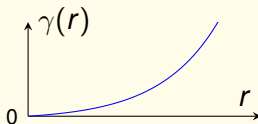
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Definition (Control system)

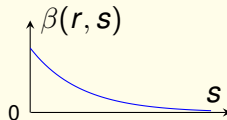
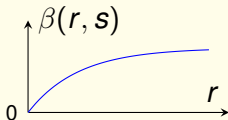
$\Sigma := (X, \mathcal{U}, \phi, Y, h)$ consisting of:

- 1 State space X
- 2 Input value space U
- 3 Input space $\mathcal{U}$ (normed linear subspace of $\{u \mid u: \mathbb{R}_+ \rightarrow U\}$),
- 4 Flow map $\phi: \mathbb{R}_+ \times X \times \mathcal{U} \rightarrow X$, $(x, u) \mapsto \phi(\cdot, x, u)$.
- 5 Output-value space $(Y, \|\cdot\|_Y)$.
- 6 Output map $h: X \rightarrow Y$.

- We assume:
 Σ satisfies the identity, causality, and cocycle properties.
- $y(t, x, u) := h(\phi(t, x, u))$, $(x, u) \in X \times \mathcal{U}$.



$$\mathcal{K}_\infty = \{\gamma \in \mathcal{C}(\mathbb{R}_+, \mathbb{R}_+): \gamma \text{ is strictly increasing, unbounded, } \gamma(0) = 0\}.$$



$$\mathcal{KL} := \{\beta \in \mathcal{C}(\mathbb{R}_+ \times \mathbb{R}_+, \mathbb{R}_+): \forall s \geq 0: \beta(\cdot, s) \in \mathcal{K}_\infty \text{ and} \\ \forall r > 0: \beta(r, \cdot) \text{ strictly decreasing to zero}\}.$$

Input-to-output stability

Definition (Sontag, 1989; Jiang, Teel, Praly, 1994)

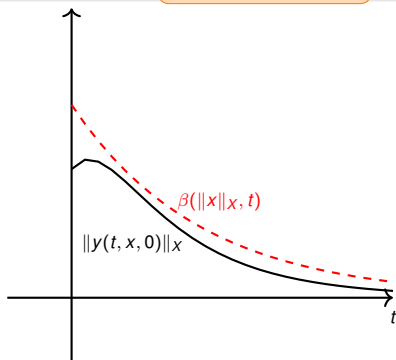
$$\text{IOS} \Leftrightarrow \|y(t, x, u)\|_X \leq \beta(\|x\|_X, t) + \gamma(\|u\|_U), \quad \forall x, t, u.$$

increasing in $\|x\|_X$

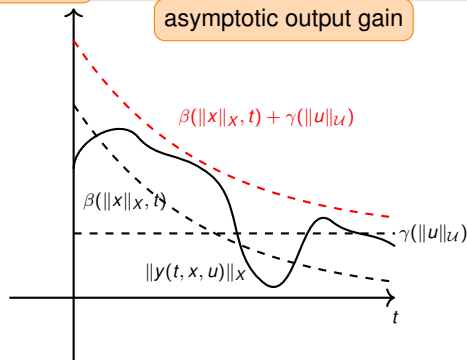
decreasing to 0 in t

$\gamma(0) = 0$, increasing

asymptotic output gain



(a) $u \equiv 0$



(b) $u \neq 0$

Input-to-output stability

Definition (Sontag, 1989; Jiang, Teel, Praly, 1994)

$$\text{IOS} \quad :\Leftrightarrow \quad \|y(t, x, u)\|_X \leq \beta(\|x\|_X, t) + \gamma(\|u\|_U), \quad \forall x, t, u.$$

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Possible choices of y

- $y = \text{state} \Rightarrow \text{IOS} = \text{input-to-state stability (ISS)}$
- $y = \text{selected coordinates of the state} \Rightarrow \text{IOS} = \text{partial (robust) stability}$
- $y = \text{tracking error}$
- $y = \text{observation error}$

ISS and IOS characterizations for ODEs

- Sontag, Wang. *On characterizations of the input-to-state stability property*. SCL, 1995.
- Sontag, Wang. *New characterizations of input-to-state stability*. IEEE TAC, 1996.
- Ingalls, Sontag, Wang. *Generalizations of asymptotic gain characterizations of ISS to input-to-output stability*. ACC, 2001.

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ISS characterizations for infinite-dimensional systems

- M., Wirth. *Characterizations of input-to-state stability for infinite-dimensional systems*, TAC, 2018.

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Applications

- Non-coercive Lyapunov theory for nonlinear systems
- Small-gain theorems for nonlinear (in)finite networks with ∞ -dim components
- Relations of ISS and energy-based stability notions
- Lyapunov-Krasovskii theory of time-delay systems

ISS and IOS characterizations for ODEs

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Today: IOS of infinite-dimensional systems

Motivation: Uniform global asymptotic stability for ODEs

$$\dot{x} = f(x), \quad f \text{ is Lipschitz.} \quad (\text{ODE})$$

Definition (UGAS (= IOS with $y = \phi$ and no inputs))

(ODE) is **uniformly globally asymptotically stable (UGAS)** if $\exists \beta \in \mathcal{KL}$:

$$x \in \mathbb{R}^n, \quad t \geq 0 \quad \Rightarrow \quad |\phi(t, x)| \leq \beta(|x|, t).$$

Proposition (UGAS Superposition Theorem for ODEs)

(ODE) is **UGAS** $\Leftrightarrow$ the following properties hold:

- (ODE) is **forward complete**: all solutions exist on $\mathbb{R}_+$.
- (ODE) is **locally stable**: $\exists \sigma \in \mathcal{K}_\infty$ and $r > 0$:

$$|x| \leq r, \quad t \geq 0 \quad \Rightarrow \quad |\phi(t, x)| \leq \sigma(|x|).$$

- (ODE) is **globally attractive**:

$$x \in \mathbb{R}^n \quad \Rightarrow \quad \lim_{t \rightarrow \infty} |\phi(t, x)| = 0.$$

Can this result be extended to ∞ -dim systems?

$$X = l_2 := \left\{ (x_i)_{i=0}^{\infty} \subset \mathbb{R} : \sum_{i=0}^{\infty} |x_i|^2 < \infty \right\}.$$

Consider the following system on X , with $a > 0$ small enough.

$$\dot{x}_i = -\frac{1}{i+1} x_i, \quad i = 0, 1, \dots$$

- All modes converge to 0.
- But the higher is the mode, the slower it converges
- There is no uniform decay rate for all initial conditions.

This system is stable and globally attractive, but not UGAS!

Conjecture: Uniform global asymptotic stability for ∞ -dim systems

Definition (UGAS (= IOS with $y = \phi$ and no inputs))

Σ is **uniformly globally asymptotically stable (UGAS)** if $\exists \beta \in \mathcal{KL}$:

$$x \in X, \quad t \geq 0 \quad \Rightarrow \quad \|\phi(t, x)\|_X \leq \beta(\|x\|_X, t).$$

Conjecture (UGAS Superposition Theorem for ∞ -dim systems)

Σ is **UGAS** $\Leftrightarrow$ the following properties hold:

- Σ is **forward complete**: all solutions exist on $\mathbb{R}_+$.
- Σ is **locally stable**: $\exists \sigma \in \mathcal{K}_\infty$ and $r > 0$:

$$\|x\|_X \leq r, \quad t \geq 0 \quad \Rightarrow \quad \|\phi(t, x)\|_X \leq \sigma(\|x\|_X).$$

- Σ is **uniformly globally attractive (UGATT)**:

$$R > 0 \quad \Rightarrow \quad \lim_{t \rightarrow \infty} \sup_{\|x\|_X \leq R} \|\phi(t, x)\|_X = 0.$$

Example (Bachmann, Dashkovskiy, M. [TAC, 2026]; M., Wirth [TAC, 2018])

I want to construct a system

$$\dot{x} = f(x) \quad (\Sigma)$$

- f is Lipschitz continuous on bounded balls
- Σ is forward complete: All solutions exist on $\mathbb{R}_+$
- Σ is locally exponentially stable
- Σ is uniformly globally attractive: For any $\varepsilon > 0$, there is $T = T(\varepsilon) > 0$:

$$x \in X, \quad t \geq T \quad \Rightarrow \quad \|\phi(t, x)\|_X \leq \varepsilon.$$

- Σ does not have bounded finite-time reachability sets:

$\exists \tau > 0, C > 0$: $\phi([0, \tau] \times \{x \in X : \|x\|_X \leq C\})$ is an unbounded set.

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X has to be infinite-dimensional! And f has to be nonlinear!

For nonlinear ∞ -dim systems, FC does not imply BRS

$$X = l_2 := \left\{ (x_i)_{i=0}^{\infty} \subset \mathbb{R} : \sum_{i=0}^{\infty} |x_i|^2 < \infty \right\}.$$

Consider the following system on X , with $a > 0$ small enough.

$$\begin{aligned}\dot{x}_0 &= -x_0 - ax_0^3, \\ \dot{x}_i &= -x_i + x_i|x_i|(x_0 - 1) - \frac{1}{i^2}x_i^3, \quad i \in \mathbb{N}.\end{aligned}$$

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Literature for those who like counterexamples

- Bachmann, Dashkovskiy, M. *Characterization of input-to-output stability for infinite-dimensional systems*, IEEE TAC, 2026.
- M., Wirth. *Characterizations of input-to-state stability for infinite-dimensional systems*, IEEE TAC, 2018.
- Mancilla-Aguilar, Haimovich. *Forward completeness does not imply bounded reachability sets and global asymptotic stability is not necessarily uniform for time-delay systems*. Automatica, 2024.
- Chaillet, Wirth, M., Brivadis. *For time-invariant delay systems, global asymptotic stability does not imply uniform global attractivity*. L-CSS, 2024.

Theorem: Uniform global asymptotic stability for ∞ -dim systems

UGAS Superposition Theorem for ∞ -dim systems I

Σ is **UGAS** $\Leftrightarrow$ the following properties hold:

- Σ has **bounded reachability sets**: all solutions exist on $\mathbb{R}_+$, and

$$\tau \geq 0, \quad R > 0 \quad \Rightarrow \quad \sup_{\|x\|_X < R, \quad t < \tau} \|\phi(t, x)\|_X < \infty.$$

- Σ is **locally stable**: $\exists \sigma \in \mathcal{K}_\infty$ and $r > 0$:

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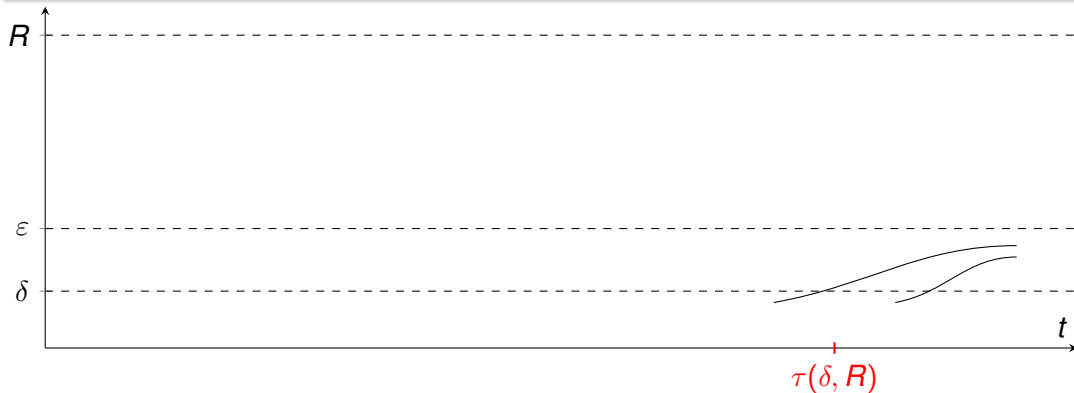
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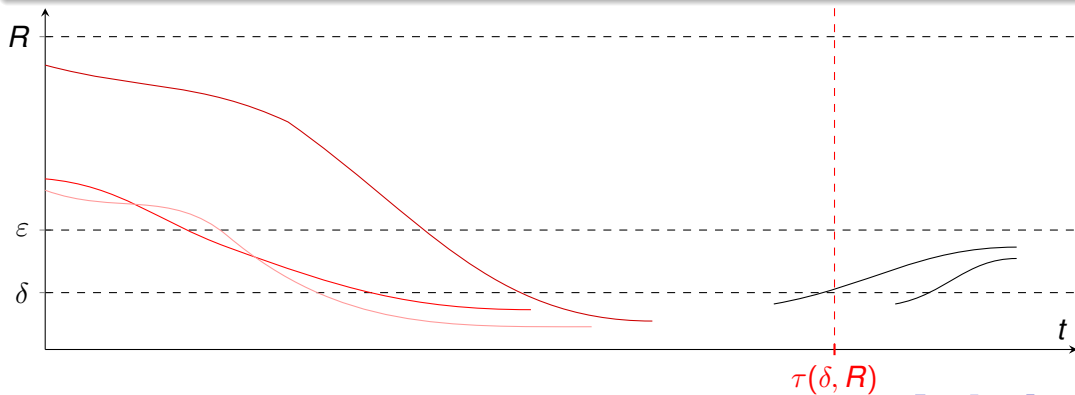


Theorem: Uniform global asymptotic stability for ∞ -dim systems

Definition (Weak UGATT)

Σ is **weakly uniformly globally attractive (weakly UGATT)**: $\forall \delta > 0, R > 0 \exists \tau = \tau(\delta, R)$

$$\|x\| \leq R \Rightarrow \exists t \leq \tau(\delta, R) : \|\phi(t, x)\|_X < \delta.$$

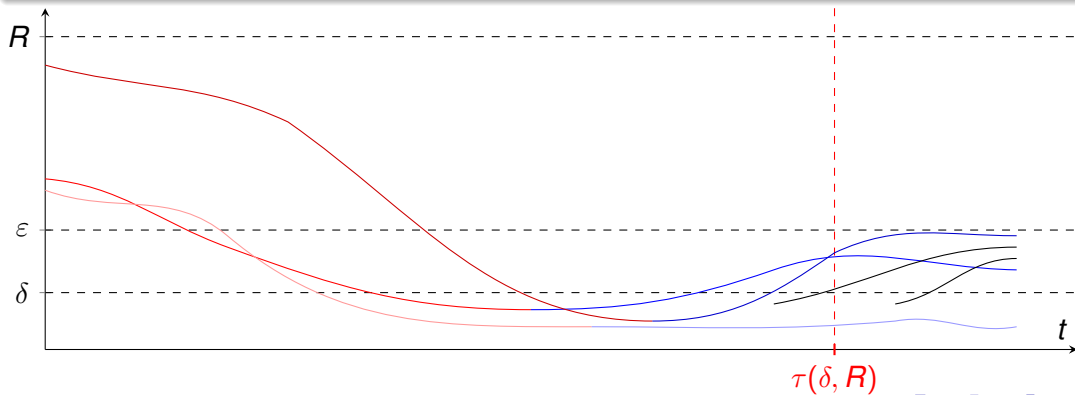


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Theorem: Uniform global asymptotic stability for ∞ -dim systems

UGAS Superposition Theorem for ∞ -dim systems

UGAS $\Leftrightarrow$ BRS $\wedge$ LS $\wedge$ weak UGATT

Theorem: Uniform global asymptotic stability for ∞ -dim systems

UGAS Superposition Theorem for ∞ -dim systems

$$\text{UGAS} \Leftrightarrow \text{BRS} \wedge \text{LS} \wedge \text{weak UGATT}$$

Proved in (as a corollary of the main result which is the criteria for ISS)

- M., Wirth. *Characterizations of input-to-state stability for infinite-dimensional systems*, TAC, 2018.

How to check these conditions?

- **Lyapunov criteria for BRS**
 - Bachmann, M. *Lyapunov characterization of boundedness of reachability sets for infinite-dimensional systems*. Submitted to IEEE TAC, 2026.
- **Lyapunov criteria for LS:** very classical
- **Lyapunov criteria for weak UGATT**
 - M., Wirth. *Non-coercive Lyapunov functions for infinite-dimensional systems*, JDE, 2019.
 - Jacob, M., Partington, Wirth. *Noncoercive Lyapunov functions for input-to-state stability of infinite-dimensional systems.*, SICON, 2020.

Local stability for systems with inputs

Definition (Output-uniform local stability (OULS))

Σ is OULS $:= \exists \sigma, \gamma \in \mathcal{K}_\infty, r > 0$:

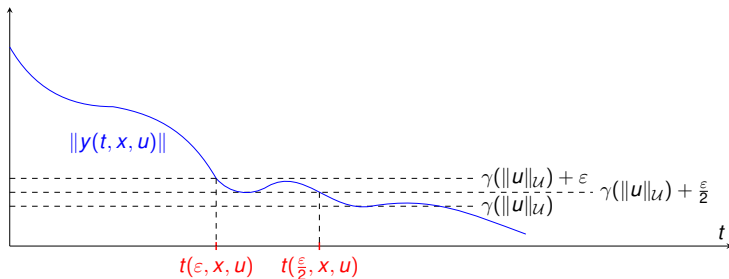
$$\|x\|_X \leq r, \quad \|u\|_U \leq r, \quad t \geq 0 \quad \Rightarrow \quad \|y(t, x, u)\|_Y \leq \sigma(\|x\|_X) + \gamma(\|u\|_U)$$

Uniform attractivity property

Definition (Output-uniform asymptotic gain property (OUAG))

$\exists \gamma \in \mathcal{K}_\infty: \forall \varepsilon, r, s > 0: \exists \tau = \tau(\varepsilon, r, s) \in \mathbb{R}_+$:

$$\|x\|_X \leq r, \|u\|_{\mathcal{U}} \leq s, t \geq \tau \Rightarrow \|y(t, x, u)\|_Y \leq \varepsilon + \gamma(\|u\|_{\mathcal{U}}).$$



IOS superposition theorem I

Theorem (IOS superposition theorem; Bachmann, Dashkovskiy, M., IEEE TAC, 2026)

Let $\Sigma := (X, \mathcal{U}, \phi, Y, h)$. Then,

$$IOS \Leftrightarrow y(\cdot) \text{ is a bounded map} \wedge OULS \wedge OUAG.$$

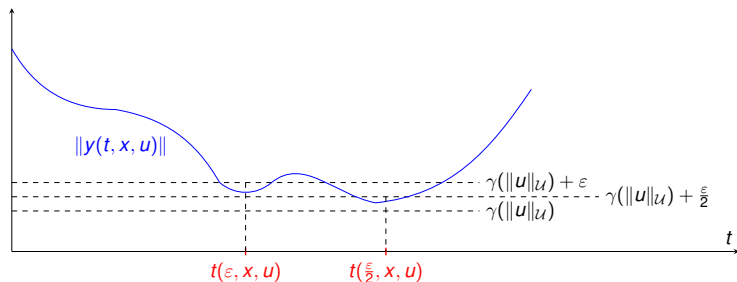
The condition that $y(\cdot)$ is a bounded map, cannot be dropped.

Uniform weak attractivity property

Definition (Output-uniform limit property (OULIM))

$\exists \gamma \in \mathcal{K}_\infty: \forall \varepsilon, r, s > 0: \exists \tau = \tau(\varepsilon, r, s) \in \mathbb{R}_+:$

$$\|x\|_X \leq r, \|u\|_U \leq s \Rightarrow \exists t \leq \tau: \|y(t, x, u)\|_Y \leq \varepsilon + \gamma(\|u\|_U).$$



IOS superposition conjecture

We would like to prove:

$$\text{IOS} \Leftrightarrow y(\cdot) \text{ is a bounded map} \wedge \text{OULS} \wedge \text{OULIM}.$$

IOS superposition conjecture

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This indeed works, if $y = \phi$:

Corollary (Superposition theorem for systems with full-state output)

Let $\Sigma := (X, \mathcal{U}, \phi, Y, h)$ have full-state output ($y = \phi$). Then:

$$\text{ISS} \Leftrightarrow \text{BRS} \wedge \text{ULS} \wedge \text{ULIM}.$$

IOS superposition conjecture

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$$\text{ISS} \Leftrightarrow \text{BRS} \wedge \text{ULS} \wedge \text{ULIM}.$$

$$y \neq \phi \Rightarrow \text{this criterion is not true.}$$

Local stability for systems with inputs

Definition (Output-uniform global stability (OUGS))

Σ is OUGS $:= \exists \sigma, \gamma \in \mathcal{K}_\infty$:

$$x \in X, \quad u \in \mathcal{U}, \quad t \geq 0 \quad \Rightarrow \quad \|y(t, x, u)\|_Y \leq \sigma(\|x\|_X) + \gamma(\|u\|_U)$$

Definition (Output Lagrange stability (OL))

Σ is OL $:= \exists \sigma, \gamma \in \mathcal{K}_\infty$:

$$x \in X, \quad u \in \mathcal{U}, \quad t \geq 0 \quad \Rightarrow \quad \|y(t, x, u)\|_Y \leq \sigma(\|y(0, x, u)\|_Y) + \gamma(\|u\|_U)$$

$$y = \phi \quad \Rightarrow \quad \text{OUGS} = \text{OL}.$$

$y \neq \phi \quad \Rightarrow \quad \text{OUGS} \neq \text{OL}, \quad \text{a major difficulty in analysis of IOS in compare to ISS.}$

IOS superposition theorem II

Theorem (IOS superposition theorem; Bachmann, Dashkovskiy, M., IEEE TAC, 2026)

Let $\Sigma := (X, \mathcal{U}, \phi, Y, h)$, and let

- h be $\mathcal{K}$ -bounded: $\exists \sigma_1, \gamma_1 \in \mathcal{K}_\infty$:

$$x \in X \quad \Rightarrow \quad \|h(x)\|_Y \leq \sigma_1(\|x\|_X).$$

Then,

$$\text{IOS} \wedge \text{OL} \quad \Leftrightarrow \quad \text{OULIM} \wedge \text{OL}.$$

IOS superposition theorem II

Theorem (IOS superposition theorem; Bachmann, Dashkovskiy, M., IEEE TAC, 2026)

Let $\Sigma := (X, \mathcal{U}, \phi, Y, h)$, and let

- h be $\mathcal{K}$ -bounded: $\exists \sigma_1, \gamma_1 \in \mathcal{K}_\infty$:

$$x \in X \Rightarrow \|h(x)\|_Y \leq \sigma_1(\|x\|_X).$$

Then,

$$IOS \wedge OL \Leftrightarrow OULIM \wedge OL.$$

Potential applications

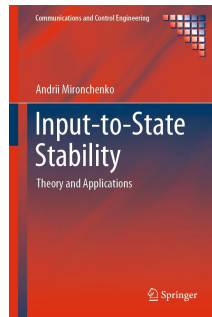
- IOS Lyapunov-Krasovskii theory for delay systems
- Non-coercive Lyapunov theory
- IOS small-gain theory
- Relations of IOS and energy-based stability notions

Main results

- $\text{IOS} \Leftrightarrow \text{OUAG} \wedge \text{OULS} \wedge y(\cdot)$ is a bounded map.
- $\text{IOS} \wedge \text{OL} \Leftrightarrow \text{OULIM} \wedge \text{OL} \wedge h$ is K -bounded.
- Boundedness of reachability sets is important!

More theory, examples & applications:

- Bachmann, Dashkovskiy, M. *Characterization of input-to-output stability for infinite-dimensional systems*, IEEE TAC, 2026.
- M., Wirth. *Characterizations of input-to-state stability for infinite-dimensional systems*, IEEE TAC, 2018.
- Bachmann, M. *Lyapunov characterization of boundedness of reachability sets for infinite-dimensional systems*. Submitted to IEEE TAC, 2026.
- Bachmann, Dashkovskiy, M. *An IOS small-gain theorem for networks of distributed parameter systems with outputs*. Submitted to CDC 2026.



SCINDIS 2026

5th Workshop on Stability and Control of Infinite-Dimensional Systems

September 30 – October 2, 2026 in Bayreuth, Germany

Invited speakers

Nikolaos Bekiaris-Liberis (*TU Crete*)
Lucas Brivadis (*L2S, CNRS*)
Emilia Fridman (*U Tel Aviv*)
Jochen Glück (*U Wuppertal*)
Martin Gugat (*FAU Erlangen-Nürnberg*)
Iasson Karafyllis (*NTU Athens*)
Rami Katz (*U Tel Aviv*)
Volker Mehrmann (*TU Berlin*)
Kirsten Morris (*U Waterloo*)
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